

Highest Voltage Sag and Swell Compensation using Single Phase Matrix Converter with Four Controlled Switches

Abstract: The aim of this paper is to explain the control algorithm very clearly and precisely to achieve maximum voltage sag compensation of 52% and infinite quantity of voltage swell using direct converter based DVR. The proposed DVR topology has a single phase matrix converter (SPMC), series transformer and LC filter. If the duty cycle of the PWM is digitally computed by measuring the available voltage at the supply and the percentage of voltage sag, it is possible to mitigate 52% of voltage sag and infinite quantity of voltage swell with the THD less than 1%. Matlab Simulation results are presented for validating the analysis.

Streszczenie: Celem artykułu jest precyzyjne wyjaśnienie algorytmu sterowania w celu uzyskania maksymalnej kompensacji zapadu napięcia wynoszącej 52% i wzrostu napięcia przy użyciu rejestratora DVR z bezpośrednim przetwornikiem. Proponowana topologia DVR ma jednofazowy konwerter macierzy (SPMC), transformator szeregowy i filtr LC. Jeżeli cykl pracy PWM jest obliczany cyfrowo poprzez pomiar dostępnego napięcia na zasilaniu i procentu zapadu napięcia, możliwe jest złagodzenie 52% zapadu napięcia i wielkości wzrostu napięcia przy THD mniejszym niż 1%. Wyniki Matlab Simulation są prezentowane w celu walidacji analizy. (Kompensacja zapadów i wzrostu napięcia przy wykorzystaniu jednofazowego przekształtnika macierzowego z czterema przełącznikami)

Keywords: Voltage Sag, Voltage Swell, Single Phase Matrix Converter, DVR, Series Transformer, Digital PWM technique.

Słowa kluczowe: zapad napięcia, wzrost napięcia, jednofazowy przetwornik matrycowy, DVR, transformator szeregowy, technika PWM

Introduction

Though we have many power quality issues like voltage sag, voltage swell, flicker, harmonics, etc., voltage sag is considered to be the severe issue as it affects the operation of sensitive loads like computer, micro controller, Digital Signal Processor, FPGA. As most of the industries are automated, the entire operation of the industries depends upon the operating condition of these embedded systems and sensitive loads. When sag or swell occurs in the industrial areas, these sensitive loads are getting affected, leading to immoral operation of the entire industry [1, 2]. For the compensation of voltage sag, Dynamic Voltage Restorer (DVR) considered to be an effective device when compared to other devices like UPS, STATCOM [3-5].

DVR is a series compensator, which is used to add the compensating voltage in series with the line voltage in order to mitigate voltage sag, swell, harmonics, flicker, etc. A conventional DVR has an energy storage device (which may be a battery bank or capacitor or super capacitor), an inverter to convert the DC power in the energy storage device to AC power and a series transformer to inject the AC power generated by the inverter, in series with the line voltage. When a power quality issue occurs on the supply side, the inverter synthesizes the required compensating voltage by taking power from the energy storage devices and injects the compensating voltage in series with the line voltage using the series transformer [6-8]. The compensating range and duration of mitigation of voltage sag and swell, of this topology is based on the rating of the energy storage devices. This conventional DVR has disadvantages like heavy weight, volume, uneconomical, more maintenance due to the energy storage devices [9-11]. In order to overcome, these disadvantages, recently DVRs based on direct converters are proposed. In this topology, the energy storage devices are not used. Instead the power is taken from the supply side itself to mitigate the power quality issues. As the power is taken from the supply side to mitigate the power quality issues, this topology uses direct converters to synthesize the compensating voltage. A series transformer is used to inject the output voltage of the direct converter, in series with the line voltage. So when a voltage sag or swell occurs, the direct converter will synthesize the required compensating voltage by taking

power from the supply side and the compensating voltage is added in series with the line voltage using the series transformer. As this topology didn't use energy storage devices, it is not having disadvantages like topology based on energy storage devices. The compensating range and the mitigating duration of this topology is based upon the direct converter topology, modulating techniques and the availability of input voltage for the direct converter [12-16].

In the literature, very few publications are available for the DVRs based on the direct converters as it is recent technique. Out of those publications, the topology presented in [17] can mitigate 50% of voltage sag and 100% of swell by taking power from the same phase. The topologies presented in [18, 19] can mitigate 33% of voltage sag and 100% of voltage swell by taking power from the different phases. Though the topologies in [20-22] are based on direct converters, they can mitigate voltage sag, swell and also single outage. Based on the modulating techniques, the voltage sag and swell compensating range could be improved [23, 24]. In this paper, the DVR is realized using a Single Phase Matrix Converter (SPMC), which is a direct converter. The single phase matrix converter is realized using only four controlled switches but so far the single matrix converter is been realized using 8 controlled switches. As it is realized with 4 controlled switches, the generation of PWM pulses are very easy while compared to generation of switching pulses for 8 controlled switches. With the presence of 8 switches, the commutation problem occurs. But with 4 controlled switches, no commutation problems occurs as there is one bidirectional switch for each phase. In this paper, the achievement of 52% voltage sag compensation is clearly explained in a detail manner.

It is observed from the analysis that to mitigate voltage sag and swell by taking power from the same phase, using a DVR based on direct converter, by ordinary PWM technique, it is possible to achieve only 22% of sag and swell compensation. If the duty cycle of the PWM is digitally computed by measuring the available voltage at the supply side and the percentage of voltage sag, it is possible to mitigate 52% of voltage sag and infinite quantity of voltage swell with the THD less than 1%.

Principle of operation

The topology of DVR is been shown in the figure 1. It has a single phase matrix converter, a LC filters at the input side of the single phase matrix converter and another LC filter at the output side of the single phase matrix converter, and a series transformer. The LC filters are to minimize the harmonics due to switching both at the input side and also at the output side. The single phase matrix converter has four bidirectional switches S1, S2, S3 and S4 as shown in the figure 1. Each bidirectional switch has only one controlled switch. The topology of the bidirectional switch is shown in the figure 2 where the switch S could be IGBT, MOSFET or BJT. When the supply voltage is at rated value, the switches S3 and S4 are closed and the other two switches S1 and S2 are open. In this condition, the secondary of the series transformer is short circuited which results in zero voltage injection and the load voltage is maintained at its rated value. When the voltage sag occurs, the DVR will synthesis the compensating voltage by taking power from the same phase and operating the switches S1, S4 and S3 alternatively. The compensating voltage is added in phase with the supply voltage through the series transformer. The turns ratio of the series transformer is 1:1.

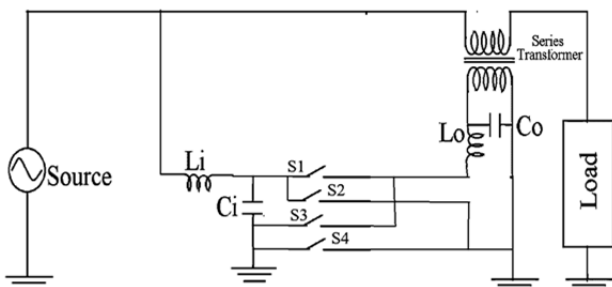


Fig. 1. Topology of the DVR

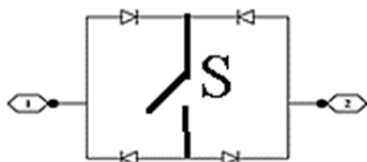


Fig. 2. Topology of the Bidirectional Switch

When swell occurs, the DVR will operate the switches S3, S4 and S2 alternatively such that the compensating voltage is added out of phase with the supply voltage through the series transformer.

Control algorithm

From the figure.1 we could observe that the load voltage V_{load} is equal to the summation of source voltage V_{supply} and the compensating voltage $V_{compensating}$ synthesized by the SPMC.

$$(1) \quad V_{supply} + V_{compensating} = V_{load}$$

We could write compensating voltage as the difference between the rated supply voltage and the voltage available at the supply side.

$$(2) \quad V_{compensating} = V_{rated} - V_{supply}$$

As the SPMC, takes power from the same phase to compensate both sag and swell, we could write compensating voltage generated by the SPMC as

$$(3) \quad V_{compensating} = V_{supply} \times T_{on}$$

The on time of the PWM should be according to the existing value of sag or swell occurrence in the supply side. So

$$(4) \quad T_{on} = V_{compensating} \div V_{supply}$$

The supply side voltage is measured and the peak value of the supply voltage is calculated using single phase dq theory [25]. The difference between the rated voltage and the supply side voltage gives the value of the compensating voltage as given in equation (2). The ratio of the compensating voltage and the supply voltage gives the percentage T_{on} period of the switching pulse, as per the equations (3) and (4). It could be understood from the figure 1 that in order to compensate sag, the SPMC should inject a voltage in phase with the supply voltage. To do so, the switches S1 and S3 should be alternatively modulated and the switch S4 should be closed and S3 should be open. The figure 3 shows the logic of generating the PWM for all the four switches.

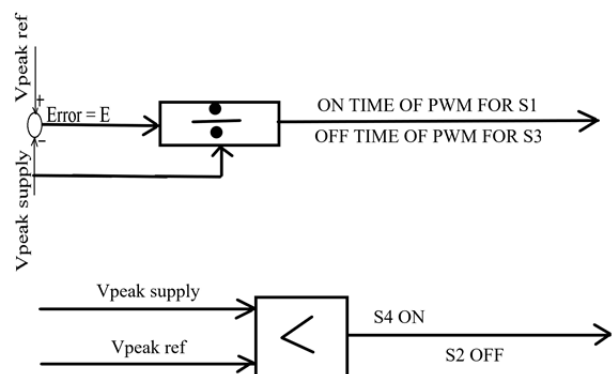


Fig. 3. Block diagram for PWM generation for voltage sag compensation

A micro controller compares the peak value of the supply voltage with the reference voltage value. If the peak value of the supply voltage is less than the peak value of the reference voltage immediately the S4 is closed and S3 is opened. The same micro controller is used to generate the PWM pulses for switch S1 by dividing the magnitude of the compensating voltage (error signal) by the peak value of the supply voltage. The complimentary PWM of switch S1 is the PWM for switch S3. In this logic the PWM for all the four switches are generated. Moreover, Table 1 shows the sag compensating range of 22% by the SPMC when ordinary PWM technique is used. By using digital PWM technique it is possible to compensate a voltage sag of 52% as shown in the table 2. It could be observed from the table 2 that the compensated load voltage is maintained within the IEEE standard value. It is very well known that for both the voltage and the frequency, variation allowed as per the IEEE standard is $\pm 5\%$.

In the same approach, voltage swell is mitigated. It could be understood from the figure 1 that in order to compensate voltage swell, the SPMC should inject a voltage out of phase with the supply voltage. To do so, the switches S2 and S4 should be alternatively modulated and the switch S3 should be closed and S1 should be open. The figure 4 shows the logic of generating the PWM for all the four switches. Moreover, Table 3 shows the swell compensating range of 22% by the SPMC when ordinary PWM technique is used. By using digital PWM technique it is possible to compensate a swell of any magnitude as shown in the table 4.

Table 1. Possible Voltage Sag Compensation with ordinary PWM technique

Supply Voltage in Volts	% of Sag	Error	Duty Cycle of PWM	Compensating voltage generated by the DVR = Supply Voltage * Duty Cycle	Load Voltage = Supply Voltage + Compensating Voltage
100	0%	0	0	0	100
90	10%	10	10%	9	99
80	20%	20	20%	16	96
78	22%	22	22%	17.16	95.16
77	23%	23	23%	17.71	94.71
76	24%	24	24%	18.24	94.24
70	30%	30	30%	21	91
60	40%	40	40%	24	84
50	50%	50	50%	25	75

Table 2. Voltage Sag Compensation by Digital PWM technique

Vsupply	Sag & Error in %	Ton = Error/Vsupply	Compensating voltage = Vsupply * Ton	Load Voltage = Vsupply + Compensating Voltage
100	0	0	0	100
98	2	0.0204	2	100
96	4	0.0416	4	100
94	6	0.0638	6	100
92	8	0.0869	8	100
90	10	0.1111	10	100
88	12	0.1363	12	100
86	14	0.1627	14	100
84	16	0.190	16	100
82	18	0.2195	18	100
80	20	0.25	20	100
78	22	0.2820	22	100
76	24	0.3157	24	100
74	26	0.3513	26	100
72	28	0.3888	28	100
70	30	0.4285	30	100
68	32	0.4705	32	100
66	34	0.5151	34	100
64	36	0.5625	36	100
62	38	0.6129	38	100
60	40	0.6666	40	100
58	42	0.7241	42	100
57	43	0.7543	43	100
56	44	0.7857	44	100
55	45	0.8181	45	100
54	46	0.8518	46	100
53	47	0.8867	47	100
52	48	0.9230	48	100
51	49	0.9607	49	100
50	50	1	50	100
49	51	1	49	98
48	52	1	48	96
47	53	1	47	94

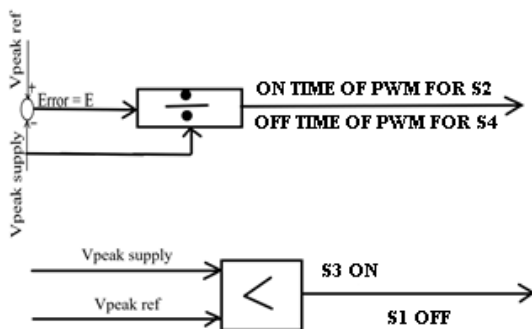


Fig. 4. Block diagram for PWM generation for voltage swell compensation

It could be observed from the table 4 that the compensated load voltage is maintained within the IEEE standard value of $\pm 5\%$ deviation throughout the voltage swell compensation.

Table 3. Possible Voltage Swell Compensation with ordinary PWM technique

Supply Voltage in Volts	Swell & Error in %	Duty Cycle of PWM	Compensating voltage = Supply Voltage * Duty Cycle	Load Voltage = Supply Voltage - Compensating Voltage
100	0	0	0	100
110	10	0.1	11	99
120	20	0.2	24	96
121	21	0.21	25.41	95.59
122	22	0.22	26.84	95.16
123	23	0.23	28.29	94.71
130	30	0.3	39	91
140	40	0.4	56	84
150	50	0.5	75	75

Table 4. Voltage Swell Compensation by Digital PWM technique

Vsupply In Volts	Swell & Error in %	Ton = Error/Vsupply	Compensating voltage = Vsupply* Ton	Load Voltage = Supply Voltage - Compensating Voltage
100	0	0	0	100
110	10	0.0909	10	100
120	20	0.1666	20	100
130	30	0.2307	30	100
140	40	0.2857	40	100
150	50	0.3333	50	100
160	60	0.375	60	100
170	70	0.4117	70	100
180	80	0.4444	80	100
190	90	0.4736	90	100
200	100	0.5	100	100
250	150	0.6	150	100
300	200	0.6666	200	100
400	300	0.75	300	100
500	400	0.8	400	100
1000	900	0.9	900	100

Simulation results

For easy understanding, the rated value of supply voltage is set with the amplitude of 100V, 50Hz. The DVR operates with the filter inductance of 1mH and filter capacitance of 15uF at the carrier frequency of 4 KHz. The resonance frequency F_r of the LC filter should be greater than the system frequency 50 Hz and less than the PWM switching frequency 4KHz. In order to minimize the size of the inductor and the capacitor, a resonance frequency F_r of 1300 Hz has been chosen. The value of L & C are obtained from the formula $F_r = 1 / (2\pi\sqrt{LC})$. The simulation model parameters are given in table 4.

Table 5. Parameters of simulation model

S.No	Aparatus Used	Ratings
1	Supply Voltage	100 Volts peak
2	RL Load	10 ohms 0.8 pf Lag
3	Series Transformer	1 kVA, 1:1 turns ratio
4	IGBT	230V, 15A
5	Filter Inductance	1 milli Henry
6	Filter Capacitance	15 micro Farad

The following figures figure.4, figure.5, figure.6 and figure7shows the ability of the control algorithm to mitigate sag from 0 to 52%.

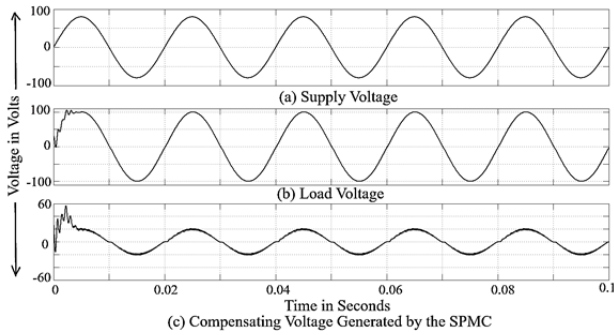


Fig. 4. Voltage Sag Compensation of 20%

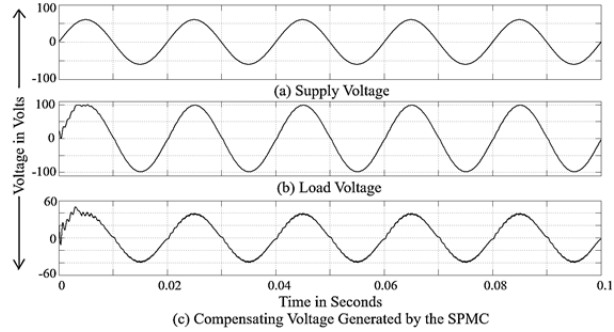


Fig. 5. Voltage Sag Compensation of 40%

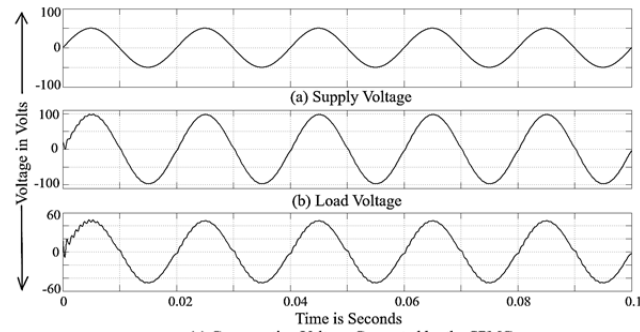


Fig. 6. Voltage Sag Compensation of 50%

Voltage swell compensation from 0 to 800% is shown in the figures figure.8, figure.9, figure.10 and figure.11.

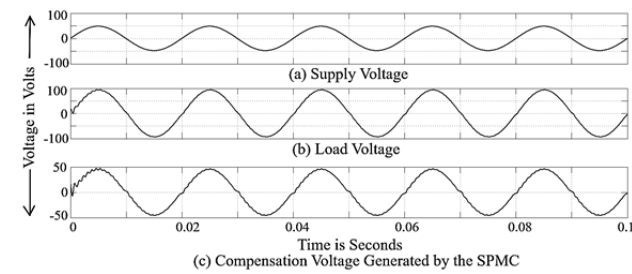


Fig. 7. Voltage Sag Compensation of 52%

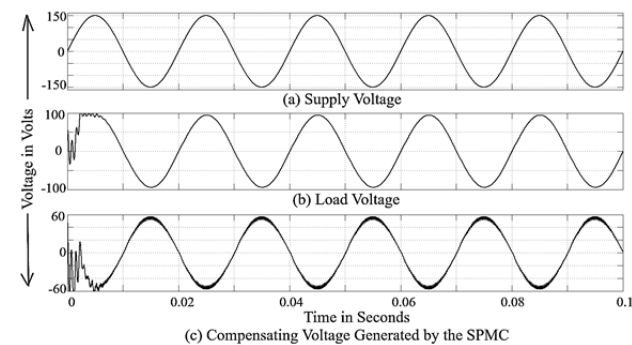


Fig. 8 50% Voltage Swell Compensation

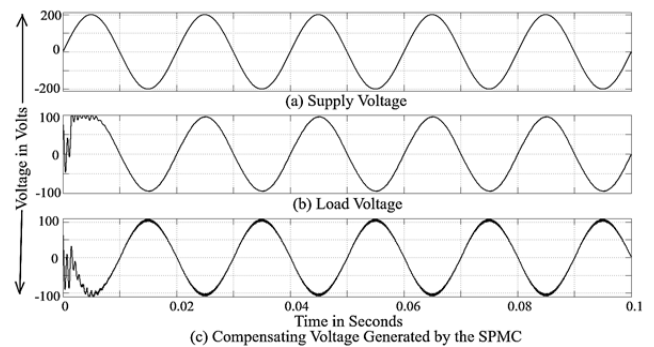


Fig. 9 100% Voltage Swell Compensation

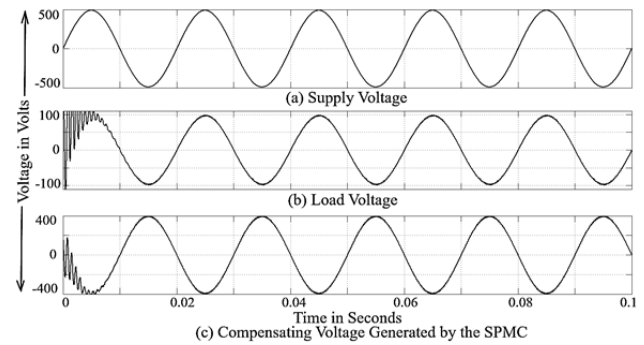


Fig. 10 400% Voltage Swell Compensation

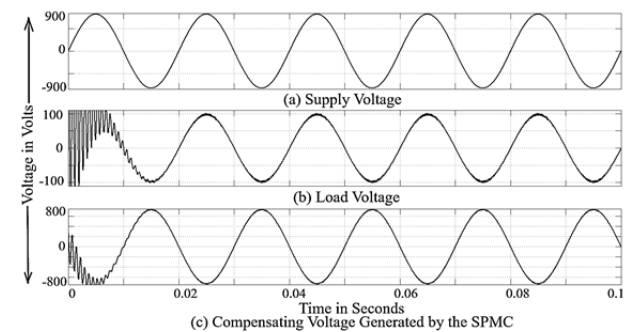


Fig. 11 800% Voltage Swell Compensation

Conclusion

In this paper, the DVR is realized using a Single Phase Matrix Converter (SPMC), which is a direct converter. The single phase matrix converter is realized using only four controlled switches but so far the single matrix converter is been realized using 8 controlled switches. As it is realized with 4 controlled switches, the generation of PWM pulses are very easy while compared to generation of switching pulses for 8 controlled switches. With the presence of 8 switches, the commutation problem occurs. But with 4 controlled switches, no commutation problems occurs as there is only one bidirectional switch for each phase. It has been demonstrated in this paper that it is possible to achieve 52% of sag compensation and unlimited amount of voltage swell compensation by digital PWM technique using a DVR based on the single phase matrix converter with THD less than 1%.

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